

## 1 CONSUMER

### 1.1 Optimisation problem

$$\max_{K_t^s, C_t, L_t^s, I_t} U_t = \beta E_t [U_{t+1}] + (1 - \eta)^{-1} \left( C_t^\mu (1 - L_t^s)^{1-\mu} \right)^{1-\eta} \quad (1.1)$$

s.t. :

$$C_t + I_t = \pi_t + K_{t-1}^s r_t + L_t^s W_t \quad \left( \lambda_t^{\text{CONSUMER}^1} \right) \quad (1.2)$$

$$K_t^s = I_t + K_{t-1}^s (1 - \delta) \quad \left( \lambda_t^{\text{CONSUMER}^2} \right) \quad (1.3)$$

### 1.2 First order conditions

$$-\lambda_t^{\text{CONSUMER}^2} + \beta \left( (1 - \delta) E_t \left[ \lambda_{t+1}^{\text{CONSUMER}^2} \right] + E_t \left[ \lambda_{t+1}^{\text{CONSUMER}^1} r_{t+1} \right] \right) = 0 \quad (K_t^s) \quad (1.4)$$

$$-\lambda_t^{\text{CONSUMER}^1} + \mu C_t^{-1+\mu} (1 - L_t^s)^{1-\mu} \left( C_t^\mu (1 - L_t^s)^{1-\mu} \right)^{-\eta} = 0 \quad (C_t) \quad (1.5)$$

$$\lambda_t^{\text{CONSUMER}^1} W_t + (-1 + \mu) C_t^\mu (1 - L_t^s)^{-\mu} \left( C_t^\mu (1 - L_t^s)^{1-\mu} \right)^{-\eta} = 0 \quad (L_t^s) \quad (1.6)$$

$$-\lambda_t^{\text{CONSUMER}^1} + \lambda_t^{\text{CONSUMER}^2} = 0 \quad (I_t) \quad (1.7)$$

## 2 FIRM

### 2.1 Optimisation problem

$$\max_{K_t^d, L_t^d, Y_t} \pi_t = Y_t - L_t^d W_t - r_t K_t^d \quad (2.1)$$

s.t. :

$$Y_t = Z_t K_t^{d\alpha} L_t^{d1-\alpha} \quad \left( \lambda_t^{\text{FIRM}^1} \right) \quad (2.2)$$

## 2.2 First order conditions

$$-r_t + \alpha \lambda_t^{\text{FIRM}^1} Z_t K_t^{\text{d}^{-1+\alpha}} L_t^{\text{d}^{1-\alpha}} = 0 \quad (K_t^{\text{d}}) \quad (2.3)$$

$$-W_t + \lambda_t^{\text{FIRM}^1} Z_t (1 - \alpha) K_t^{\text{d}^\alpha} L_t^{\text{d}^{-\alpha}} = 0 \quad (L_t^{\text{d}}) \quad (2.4)$$

$$1 - \lambda_t^{\text{FIRM}^1} = 0 \quad (Y_t) \quad (2.5)$$

## 2.3 First order conditions after reduction

$$-r_t + \alpha Z_t K_t^{\text{d}^{-1+\alpha}} L_t^{\text{d}^{1-\alpha}} = 0 \quad (K_t^{\text{d}}) \quad (2.6)$$

$$-W_t + Z_t (1 - \alpha) K_t^{\text{d}^\alpha} L_t^{\text{d}^{-\alpha}} = 0 \quad (L_t^{\text{d}}) \quad (2.7)$$

# 3 EQUILIBRIUM

## 3.1 Identities

$$K_t^{\text{d}} = K_{t-1}^{\text{s}} \quad (3.1)$$

$$L_t^{\text{d}} = L_t^{\text{s}} \quad (3.2)$$

# 4 EXOG

## 4.1 Identities

$$Z_t = e^{\epsilon_t^Z + \phi \log Z_{t-1}} \quad (4.1)$$

## 5 Equilibrium relationships (after reduction)

$$-r_t + \alpha Z_t K_{t-1}^{\text{s}^{-1+\alpha}} L_t^{\text{s}^{1-\alpha}} = 0 \quad (5.1)$$

$$-W_t + Z_t (1 - \alpha) K_{t-1}^{\text{s}^\alpha} L_t^{\text{s}^{-\alpha}} = 0 \quad (5.2)$$

$$-Y_t + Z_t K_{t-1}^{\text{s}^\alpha} L_t^{\text{s}^{1-\alpha}} = 0 \quad (5.3)$$

$$-Z_t + e^{\epsilon_t^Z + \phi \log Z_{t-1}} = 0 \quad (5.4)$$

$$\beta \left( \mu \text{E}_t \left[ r_{t+1} C_{t+1}^{-1+\mu} (1 - L_{t+1}^{\text{s}})^{1-\mu} \left( C_{t+1}^\mu (1 - L_{t+1}^{\text{s}})^{1-\mu} \right)^{-\eta} \right] + \mu (1 - \delta) \text{E}_t \left[ C_{t+1}^{-1+\mu} (1 - L_{t+1}^{\text{s}})^{1-\mu} \left( C_{t+1}^\mu (1 - L_{t+1}^{\text{s}})^{1-\mu} \right)^{-\eta} \right] \right) - \mu C_t^{-1+\mu} (1 - L_t^{\text{s}})^{1-\mu} \left( C_t^\mu (1 - L_t^{\text{s}})^{1-\mu} \right)^{-\eta} = 0 \quad (5.5)$$

$$(-1 + \mu) C_t^\mu (1 - L_t^{\text{s}})^{-\mu} \left( C_t^\mu (1 - L_t^{\text{s}})^{1-\mu} \right)^{-\eta} + \mu W_t C_t^{-1+\mu} (1 - L_t^{\text{s}})^{1-\mu} \left( C_t^\mu (1 - L_t^{\text{s}})^{1-\mu} \right)^{-\eta} = 0 \quad (5.6)$$

$$-C_t - I_t + Y_t = 0 \quad (5.7)$$

$$I_t - K_t^s + K_{t-1}^s (1 - \delta) = 0 \quad (5.8)$$

$$U_t - \beta E_t [U_{t+1}] - (1 - \eta)^{-1} \left( C_t^\mu (1 - L_t^s)^{1-\mu} \right)^{1-\eta} = 0 \quad (5.9)$$

## 6 Steady state relationships (after reduction)

$$-r_{ss} + \alpha Z_{ss} K_{ss}^{s-1+\alpha} L_{ss}^{s1-\alpha} = 0 \quad (6.1)$$

$$-W_{ss} + Z_{ss} (1 - \alpha) K_{ss}^{s\alpha} L_{ss}^{s-\alpha} = 0 \quad (6.2)$$

$$-Y_{ss} + Z_{ss} K_{ss}^{s\alpha} L_{ss}^{s1-\alpha} = 0 \quad (6.3)$$

$$-Z_{ss} + e^{\phi \log Z_{ss}} = 0 \quad (6.4)$$

$$\beta \left( \mu r_{ss} C_{ss}^{-1+\mu} (1 - L_{ss}^s)^{1-\mu} \left( C_{ss}^\mu (1 - L_{ss}^s)^{1-\mu} \right)^{-\eta} + \mu (1 - \delta) C_{ss}^{-1+\mu} (1 - L_{ss}^s)^{1-\mu} \left( C_{ss}^\mu (1 - L_{ss}^s)^{1-\mu} \right)^{-\eta} \right) - \mu C_{ss}^{-1+\mu} (1 - L_{ss}^s)^{1-\mu} \left( C_{ss}^\mu (1 - L_{ss}^s)^{1-\mu} \right)^{-\eta} = 0 \quad (6.5)$$

$$(-1 + \mu) C_{ss}^\mu (1 - L_{ss}^s)^{-\mu} \left( C_{ss}^\mu (1 - L_{ss}^s)^{1-\mu} \right)^{-\eta} + \mu W_{ss} C_{ss}^{-1+\mu} (1 - L_{ss}^s)^{1-\mu} \left( C_{ss}^\mu (1 - L_{ss}^s)^{1-\mu} \right)^{-\eta} = 0 \quad (6.6)$$

$$-C_{ss} - I_{ss} + Y_{ss} = 0 \quad (6.7)$$

$$I_{ss} - K_{ss}^s + K_{ss}^s (1 - \delta) = 0 \quad (6.8)$$

$$U_{ss} - \beta U_{ss} - (1 - \eta)^{-1} \left( C_{ss}^\mu (1 - L_{ss}^s)^{1-\mu} \right)^{1-\eta} = 0 \quad (6.9)$$

## 7 Calibrating equations

$$-0.36 Y_{ss} + r_{ss} K_{ss}^s = 0 \quad (7.1)$$

## 8 Parameter settings

$$\beta = 0.99 \quad (8.1)$$

$$\delta = 0.025 \quad (8.2)$$

$$\eta = 2 \quad (8.3)$$

$$\mu = 0.3 \quad (8.4)$$

$$\phi = 0.95 \quad (8.5)$$

## 9 Steady-state values

	Steady-state value
$r$	0.0351
$C$	0.7422
$I$	0.2559
$K^s$	10.2368
$L^s$	0.2695
$U$	-136.2372
$W$	2.3706
$Y$	0.9981
$Z$	1

## 10 The solution of the 1st order perturbation

Matrix  $P$

$$\begin{matrix} & K_{t-1}^s & Z_{t-1} \\ K_t^s & \left( 0.9631 & 0.0962 \right) \\ Z_t & \left( 0 & 0.95 \right) \end{matrix}$$

Matrix  $Q$

$$\begin{matrix} & \epsilon^Z \\ K^s & \left( 0.1012 \right) \\ Z & \left( 1 \right) \end{matrix}$$

Matrix  $R$

$$\begin{matrix} & K_{t-1}^s & Z_{t-1} \\ r_t & \left( -0.7559 & 1.3521 \right) \\ C_t & \left( 0.4919 & 0.4921 \right) \\ I_t & \left( -0.4745 & 3.8461 \right) \\ L_t^s & \left( -0.181 & 0.6282 \right) \\ U_t & \left( 0.0418 & 0.0644 \right) \\ W_t & \left( 0.4252 & 0.7238 \right) \\ Y_t & \left( 0.2441 & 1.3521 \right) \end{matrix}$$

Matrix  $S$

$$\begin{matrix} & \epsilon^Z \\ r & \left( 1.4232 \right) \\ C & \left( 0.518 \right) \\ I & \left( 4.0485 \right) \\ L^s & \left( 0.6613 \right) \\ U & \left( 0.0678 \right) \\ W & \left( 0.7619 \right) \\ Y & \left( 1.4232 \right) \end{matrix}$$

## 11 Model statistics

### 11.1 Basic statistics

	Steady-state value	Std. dev.	Variance	Loglin
$r$	0.0351	0.1893	0.0358	Y
$C$	0.7422	0.0711	0.0051	Y
$I$	0.2559	0.5284	0.2792	Y
$K^s$	10.2368	0.0469	0.0022	Y
$L^s$	0.2695	0.0867	0.0075	Y
$U$	-136.2372	0.009	0.0001	Y
$W$	2.3706	0.1011	0.0102	Y
$Y$	0.9981	0.1857	0.0345	Y
$Z$	1	0.1303	0.017	Y

### 11.2 Correlation matrix

	$r$	$C$	$I$	$K^s$	$L^s$	$U$	$W$	$Y$	$Z$
$r$	1	0.868	0.989	0.084	0.996	0.918	0.926	0.969	0.982
$C$		1	0.931	0.567	0.909	0.994	0.991	0.964	0.946
$I$			1	0.228	0.998	0.966	0.971	0.995	0.999
$K^s$				1	0.174	0.472	0.454	0.328	0.269
$L^s$					1	0.95	0.956	0.987	0.995
$U$						1	1	0.988	0.976
$W$							1	0.991	0.98
$Y$								1	0.998
$Z$									1

### 11.3 Cross correlations with the reference variable ( $Y$ )

	$\sigma[\cdot]$ rel. to $\sigma[Y]$	$Y_{t-5}$	$Y_{t-4}$	$Y_{t-3}$	$Y_{t-2}$	$Y_{t-1}$	$Y_t$	$Y_{t+1}$	$Y_{t+2}$	$Y_{t+3}$	$Y_{t+4}$	$Y_{t+5}$
$r_t$	1.019	0.116	0.234	0.378	0.548	0.745	0.969	0.623	0.343	0.121	-0.048	-0.172
$C_t$	0.383	-0.14	-0.013	0.156	0.372	0.64	0.964	0.77	0.592	0.431	0.29	0.169
$I_t$	2.845	0.044	0.168	0.323	0.511	0.735	0.995	0.684	0.426	0.216	0.05	-0.077
$K_t^s$	0.253	-0.474	-0.415	-0.313	-0.162	0.049	0.328	0.513	0.62	0.665	0.662	0.624
$L_t^s$	0.467	0.072	0.194	0.345	0.527	0.741	0.987	0.662	0.395	0.18	0.013	-0.113
$U_t$	0.049	-0.086	0.042	0.21	0.42	0.679	0.988	0.755	0.55	0.372	0.221	0.096
$W_t$	0.544	-0.076	0.052	0.219	0.428	0.685	0.991	0.752	0.541	0.361	0.208	0.083
$Y_t$	1	-0.008	0.119	0.28	0.479	0.718	1	0.718	0.479	0.28	0.119	-0.008
$Z_t$	0.702	0.023	0.149	0.306	0.499	0.729	0.998	0.699	0.448	0.242	0.078	-0.049

### 11.4 Autocorrelations

	Lag 1	Lag 2	Lag 3	Lag 4	Lag 5
$r$	0.71	0.466	0.265	0.103	-0.022
$C$	0.76	0.545	0.357	0.196	0.063
$I$	0.711	0.467	0.267	0.105	-0.02
$K^s$	0.96	0.862	0.727	0.571	0.407
$L^s$	0.709	0.465	0.264	0.102	-0.023
$U$	0.739	0.512	0.319	0.158	0.028
$W$	0.736	0.507	0.312	0.152	0.022
$Y$	0.718	0.479	0.28	0.119	-0.008
$Z$	0.713	0.471	0.271	0.11	-0.016

## 12 Impulse response functions

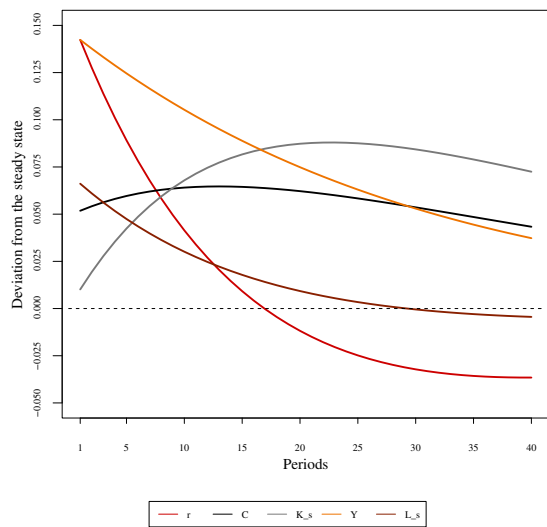


Figure 1: Impulse responses ( $r, C, K^s, Y, L^s$ ) to  $\epsilon^Z$  shock

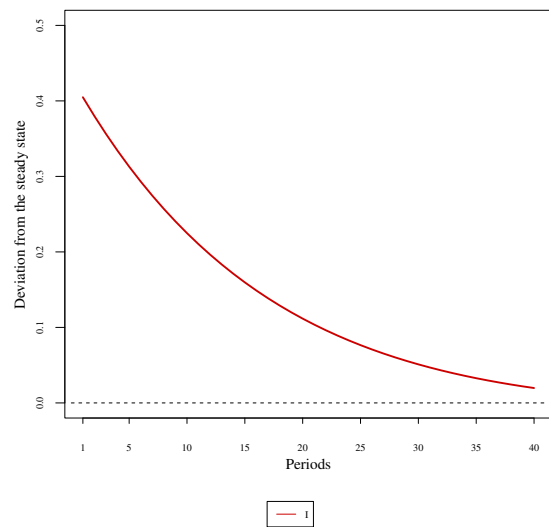


Figure 2: Impulse response ( $I$ ) to  $\epsilon^Z$  shock